

Lecture 2

Last time, constructed $U \otimes V$.

If this is your first encounter, $U \otimes V$ should feel foreign.

The construction

$$K\langle U \times V \rangle / \text{Bilinear rel's}$$

is opaque.

For example, if $\dim U_i = d_i$,
 $i=1, 2$, then what is
 $\dim U_1 \otimes U_2$?

First, some notation.

Recall that, regardless of the construction, $U \otimes V$ receives a bilinear map from the set $U \times V$:

$$i: U \times V \longrightarrow U \otimes V.$$

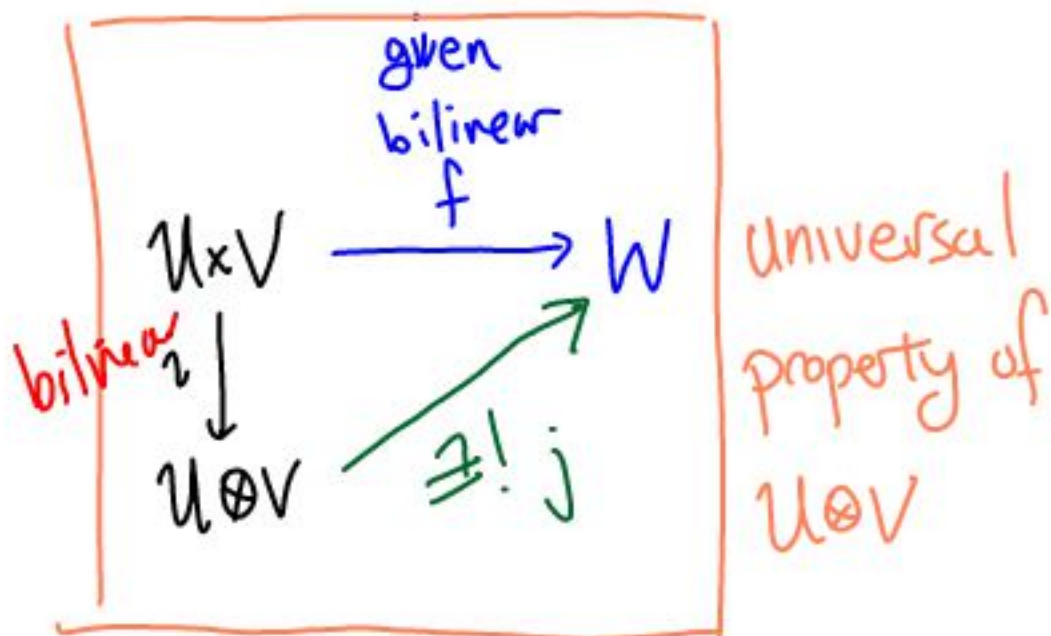
For brevity (?) we will denote the image of $(u, v) \in U \times V$ by $u \otimes v$.

That is,

$$u \otimes v := i(u, v) \in U \otimes V.$$

$K\langle U \times V \rangle := \text{vec}$
 space generated by
set $U \times V$. Has basis
 in bijection w/ $U \times V$, and
 we let $e_{(u,v)}$ denote
 a basis element last time.
 $B \subset K\langle U \times V \rangle$ was subspace
 generated by vectors: $\dots a e_{(u,v)} - e_{(u,v)}$

$$\begin{aligned} & \cdot e_{(u+u_2, v)} \\ & - e_{(u, v)} \\ & - e_{(u_2, v)} \cdot \text{etc} \end{aligned}$$



Why does construction work?
(An elaboration on last time)

By definition, f is bilinear iff

$$\cdot f(au, v) = f(u, av) = af(u, v)$$

$$\cdot f(u_1 + u_2, v) = f(u_1, v) + f(u_2, v)$$

$$\cdot f(u, v_1 + v_2) = f(u, v_1) + f(u, v_2)$$

and, hence, by defn of $\tilde{f}$ last time,

$$a\tilde{f}(e_{(u,v)}) - \tilde{f}(e_{(au,v)})$$

"

$$af(u, v) - f(au, v)$$

"

0.

That is, bilinearity of f guarantees

$\tilde{f}$ vanishes on B . Likewise,

if $\tilde{f}$ vanishes on B , and if $\tilde{f}$

is extended linearly from some

$f: U \times V \rightarrow W$, then f must be

bilinear.

Okay, so let's get a feel for $U \otimes V$.

Q: Is $i: U \times V \rightarrow U \otimes V$ injective?

A: No. For example:

$$\begin{aligned} i((au, v)) &= [e_{(au, v)}] \leftarrow \text{ie, equiv class of } e_{(au, v)} \text{ mod } \mathcal{B}. \\ &= [ae_{(u, v)}] \leftarrow \text{since } e_{(au, v)} - ae_{(u, v)} \in \mathcal{B}. \\ &= [e_{(u, av)}] \leftarrow \text{since } ae_{(u, v)} - e_{(u, av)} \in \mathcal{B}. \\ &= i((u, av)). \end{aligned}$$

More succinctly,

$$(au) \otimes v = a(u \otimes v) = u \otimes (av)$$

in $U \otimes V$. However,

Lemma i is bilinear

$$\begin{aligned} \underline{\text{pf}} \quad i(u_1 + u_2, v) &= [e_{(u_1 + u_2, v)}] \\ &= [e_{(u_1, v)} + e_{(u_2, v)}] \\ &= [ae_{(u_1, v)} + e_{(u_2, v)}] \\ &= a[e_{(u_1, v)}] + [e_{(u_2, v)}] \\ &= ai(u_1, v) + i(u_2, v). \end{aligned}$$

Likewise in the v variable. //

But the following makes $U \otimes V$ seem not so bad.

Lemma Let $\{e_i\}_{i \in I}$ be a spanning set in U , and $\{f_j\}_{j \in J}$ a spanning set for V . Then

$$\{e_i \otimes f_j\}_{(i,j) \in I \times J}$$

spans $U \otimes V$.

pf For this proof, we'll use our construction from last time.

Since any quotient map is a surjection, and $k\langle U \times V \rangle$ is spanned by $\{e_{(u,v)}\}_{(u,v) \in U \times V}$,

any element of $U \otimes V = k\langle U \times V \rangle / B$ is a finite linear combination

$$\sum a_{(u,v)} [e_{(u,v)}] \quad \leftarrow \text{summation runs over some finite collection of } (u,v) \in U \times V$$

$$\equiv \sum a_{(u,v)} u \otimes v$$

$$\equiv \sum a_{(u,v)} \left(\sum u_i e_i \right) \otimes \left(\sum v_j f_j \right)$$

since $u = \sum u_i e_i$, $u_i \in k$
 $v = \sum v_j f_j$, $v_j \in k$

$$\equiv \sum_{(u,v), i, j} a_{(u,v)} u_i v_j e_i \otimes f_j$$

Using that $\left(\sum_i u_i e_i \right) \otimes v = \sum_i u_i (e_i \otimes v)$ and likewise for $v_j f_j$.

And in fact,

Propn If $\{e_i\}_{i \in I}$ is a basis for U , and $\{f_j\}_{j \in J}$ is a basis for V , then

$\{e_i \otimes f_j\}_{(i,j) \in I \times J}$ is a basis for $U \otimes V$.

Cor If $\dim U, \dim V$ are finite, then

$$\dim(U \otimes V) = \dim U \times \dim V.$$

pf: $|I \times J| = |I| \times |J|$ when I and J are finite. //

Pf (of Prop): Since $\{e_i\}, \{f_j\}$ span, so does $\{e_i \otimes f_j\}$. So we need only prove linear independence of the collection $\{e_i \otimes f_j\}$. Assume

$\exists$ some ckn $a_{ij} \in k$ such that

$$\sum a_{ij} e_i \otimes f_j = 0 \in U \otimes V.$$

Then any linear fcn on $U \otimes V$ sends $\sum a_{ij} e_i \otimes f_j$ to 0. OTOH, define a bilinear fcn on $U \times V$ as follows:

$$\phi_{i_0 j_0} \left(\sum_i u_i e_i, \sum_j v_j f_j \right) := a_{i_0 j_0} u_{i_0} v_{j_0}$$

The linear fcn induced on $U \otimes V$ sends

$\sum a_{ij} e_i \otimes f_j$ to $a_{i_0 j_0}$; hence $a_{i_0 j_0} = 0 \forall i_0, j_0$. //

Here, we use that $\{e_i\}, \{f_j\}$ form a basis to make sure $\phi_{i_0 j_0}$ is well-defined.

Last time, we said

- direct product $\times$
- direct sum $\oplus$
- tensor product $\otimes$, and
- subspaces

were ways to make new vec.

spaces out of old. Here's

another:

Defn let V be a vec space/ $\mathbb{k}$.

We let

$$V^\vee := \text{hom}_{\mathbb{k}}(V, \mathbb{k})$$

$$:= \{ \phi: V \rightarrow \mathbb{k} \text{ s.t.} \\ \phi \text{ is } \mathbb{k}\text{-linear} \}$$

denote the collection of linear
functionals on V . We call $V^\vee$
the dual vector space of V .

The superscript is
a "check" mark.

$V^\vee$ is vocalized as
"Vee check," or
"Vee dual."

Ex If V is the vector space
of $n \times 1$ column vectors, $V^\vee$ can
be identified w/ the space of
 $1 \times n$ row vectors:

$$[b_1 \cdots b_n] : \begin{bmatrix} a_1 \\ \vdots \\ a_n \end{bmatrix} \mapsto \sum_{i=1}^n b_i a_i$$

Prop When V is finite-dim,
 $V^\vee$ is isomorphic to V , but not
 naturally. Such an isomorphism
 requires extra data—for example,
 a choice of basis. (If
 $e_1, \dots, e_n$ is a basis for V ,
 let $e_1^\vee, \dots, e_n^\vee : V \rightarrow k$ be the
 linear functions s.t.

$$e_i^\vee(e_j) = \begin{cases} 1 & i=j \\ 0 & \text{otherwise.} \end{cases}$$

The map $e_i \mapsto e_i^\vee$ induces
 a linear isom $V \xrightarrow{\cong} V^\vee$.)

Now let's combine $\otimes$ and $^\vee$.

Prop If U is finite-dim.,
 and V is any vec space,
 $\exists$ natural isomorphism

$$U^\vee \otimes V \xrightarrow{\cong} \text{hom}_k(U, V)$$

k -vec space of all
 k -linear maps from
 U to V .

Pf: Your homework.

Rmk When U, V are finite-dim, you've seen this before in some form. For example, let $U = \mathbb{R}^n, V = \mathbb{R}^m$.

Then

$$\text{hom}_{\mathbb{R}}(U, V) \cong M_{m \times n}(\mathbb{R}) \\ := \left\{ m \times n \text{ matrices} \right. \\ \left. \begin{array}{l} \text{w/ entries} \\ \text{in } \mathbb{R} \end{array} \right\}.$$

What does the matrix

$$\begin{pmatrix} 0 & \cdots & 0 & 0 & 0 \\ & \ddots & 0 & 1 & 0 \\ & & 0 & 0 & 0 \\ & & 0 & 0 & \ddots \end{pmatrix}$$

(1 in $(i, j)^{\text{th}}$ spot, 0 elsewhere) represent? It takes $e_j \in \mathbb{R}^n$ and returns the i^{th} basis vector $e_i \in \mathbb{R}^m$. This can be thought of as

$$e_j^V \otimes e_i \in U^V \otimes V.$$

In general, the matrix entries a_{ij} of a matrix A are the coefficients in

$$\sum a_{ij} e_i^V \otimes f_j.$$

Under the isomorphism $U^V \otimes V \rightarrow \text{hom}(U, V)$,

$$\sum a_{ij} e_i^V \otimes f_j \mapsto A.$$

Tensor products will return very soon! Let's begin talking about group representations.

Defn Fix a group G .

A representation of G is the data of:

- a vector space V

- a linear G -action

$$G \times V \longrightarrow V.$$

Rmk Let $GL(V)$ denote the group of invertible linear maps $V \rightarrow V$. Then a G -representation of V is the same thing as a homomorphism

$$\rho: G \longrightarrow GL(V).$$

Ex The trivial rep. is the action

$$\begin{aligned} G \times \mathbb{k} &\longrightarrow \mathbb{k} \\ (g, t) &\longmapsto t. \end{aligned}$$

This is the same data as the

constant map $G \longrightarrow \mathbb{k}^\times = GL(\mathbb{k}) = \mathbb{k} \setminus \{0\}$
 $g \longmapsto 1$

Ex Let $G = C_n := \mathbb{Z}/n\mathbb{Z}$,

the cyclic group of order n .

Set $\mathbb{K} = \mathbb{C}$, and let z be an n^{th} root of unity. Then

$$\begin{aligned} G \times \mathbb{C} &\longrightarrow \mathbb{C} \\ (a, z) &\longmapsto z^a z \end{aligned}$$

is a representation — it just rotates complex numbers. It's the same data as the group homomorphism

$$\begin{aligned} C_n &\longrightarrow \mathbb{C}^\times \\ a &\longmapsto z^a. \end{aligned}$$

Ex Let G act on a set X .

Then G acts on $\mathbb{K}\langle X \rangle$, the free vector space generated by X .

Specifically, $\mathbb{K}\langle X \rangle$ has basis

$$\{e_x\}_{x \in X}$$

and we declare $g e_x := e_{gx}$.

Extending by linearity,

$$g \left(\sum_x a_x e_x \right) = \sum_x a_x e_{gx}.$$

using G -action on X .

Here are two sub-examples:

Ex Any group G acts on itself by left multiplication:

$$\begin{aligned} G \times G &\longrightarrow G \\ (g, h) &\longmapsto gh \end{aligned}$$

So we have a representation of G on $\mathbb{K}\langle G \rangle$. This is called the regular representation of G .

Ex Let $G = S_n$ be the symmetric group on n letters. By definition, S_n acts on the set $\{1, \dots, n\}$. Hence S_n acts on $\mathbb{K}\langle \{1, \dots, n\} \rangle = \mathbb{K}^n$.

Some notation/conventions:

- When G acts on V or X , we will write $G \curvearrowright V$ or $G \curvearrowright X$.
- "Let V be a G -rep." implies the action.
- $\mathbb{K}\langle G \rangle$ will be written $\mathbb{K}G$ when G is a gp. (The group ring.)