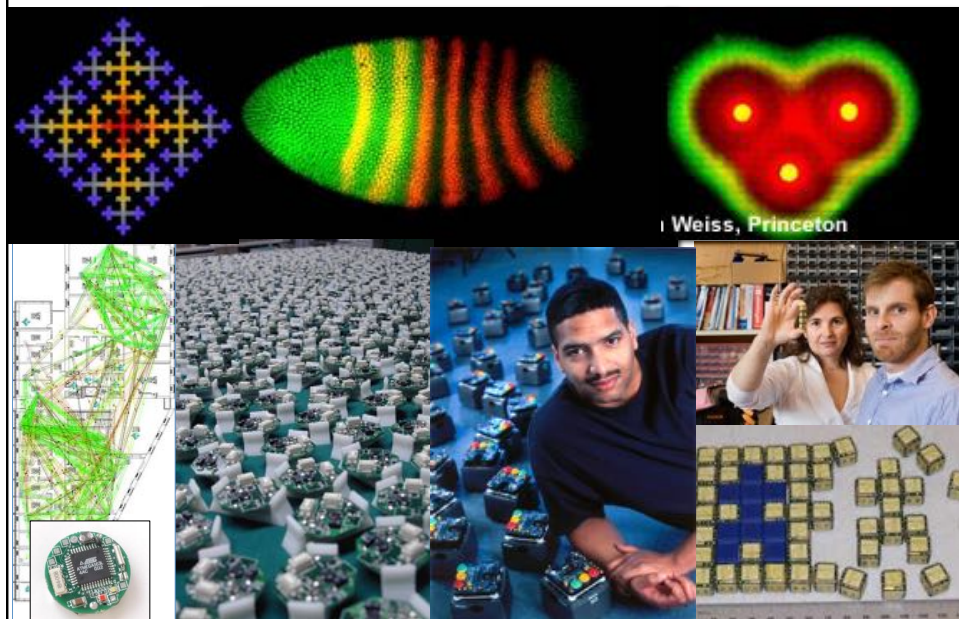


## Global-to-Local Theory CS289

### “Spatial” Computers

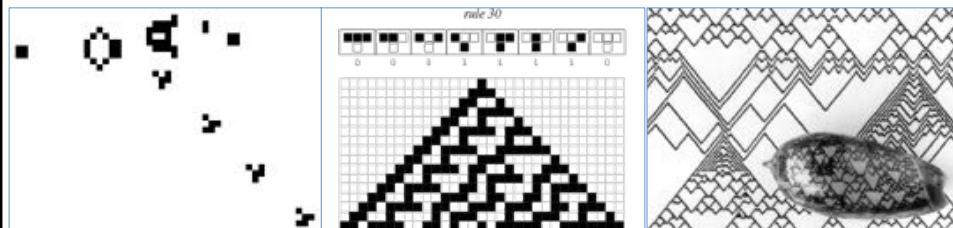


## Why Global-to-local Theory?

- Global-to-local compilers allows us to transform a class of global goals into local rules for individual agents
  - Robustness, scalability, provable..
- But they do not tell us what is *computable*
  - Local to Global is hard: e.g. Conway's Game of Life
  - But, Global to Local is possible: *Yamins, PhD 2008*

## Cellular Automata

- Stanislaw Ulam and John von Neumann (1940s)
  - Simulate “discrete” biology & physics;
  - Self-replicating machines
- Conway's Game of Life (1970s)
  - A simple intuitive rule....amazing dynamic patterns!
  - Turing Complete! (2002)
- Wolfram, A New Kind of Science, 2002
  - Systematic classification of *all* 1D two-state CA rules

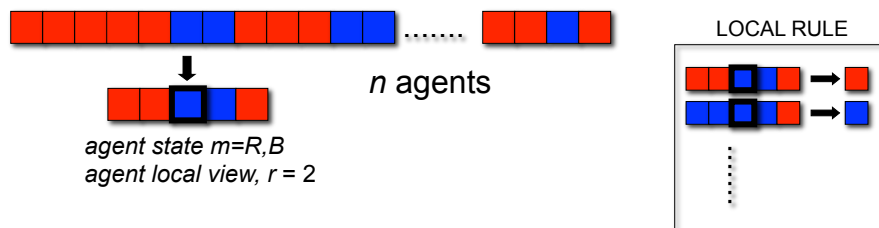


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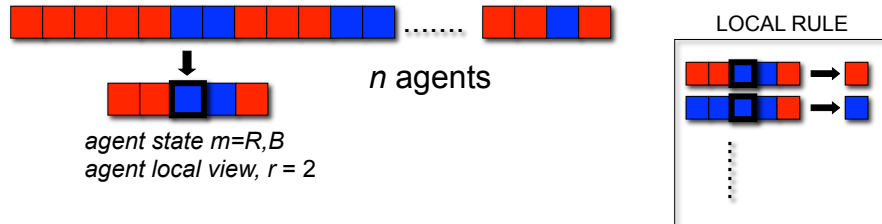
## The Setup

- 1D multi-agent system (like cellular automata)



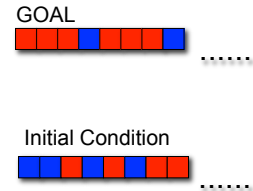
## The Setup

- 1D multi-agent system (like cellular automata)



- **Goal:**

- Self-organize target pattern
- *Scalable to more agents*
- *Any initial condition*
- *Any timing model*



## Theoretical Underpinnings

- **Local Checkability**
  - Given agent model  $(r, m)$
  - Can you design a “voting” scheme such that if every agent says 1, then the global pattern is in goal space.
  - *Necessary and Sufficient\**
- **If no check exists => no solution exists**
  - Can use to prove minimal requirements
- **If a check is available =>**
  - Can automatically produce a local rule,  
*but with slightly larger radius ( $R=2r+2$ )*
  - Provably correct, robust to asynchrony, self-repairing

## Lets do an example

- Goal Pattern: 000100010001.....0001

- 1) Design and prove correct a **local check scheme for  $r=2$**
- 2) Prove that **no local check** scheme can be designed for  $r=1$
- 3) How would you add state (change pattern) to make  $r=1$  possible?
- 4) Make a **local rule of radius  $r=4$**  for the original pattern
- 5) Prove there is **no local check of finite radius** for the half-n-half pattern ( $0^n 1^n$ ) pattern

Goal Pattern: 000100010001.....

### Local check scheme for $r=2$

Left case: 000 0001

Right case: 001 and 0001

Middle case: 00100 00010 0100 10001

**No local check for  $r=1$ :** You need to accept 000, but then all zeros would be accepted

### Local Rule Construction for $r=4$

Always possible to make a local rule of length  $R=2*r + 2$

Method is to make a "left-side" local rule (here, we do  $r=4$  on left side)

#### Special cases on left side

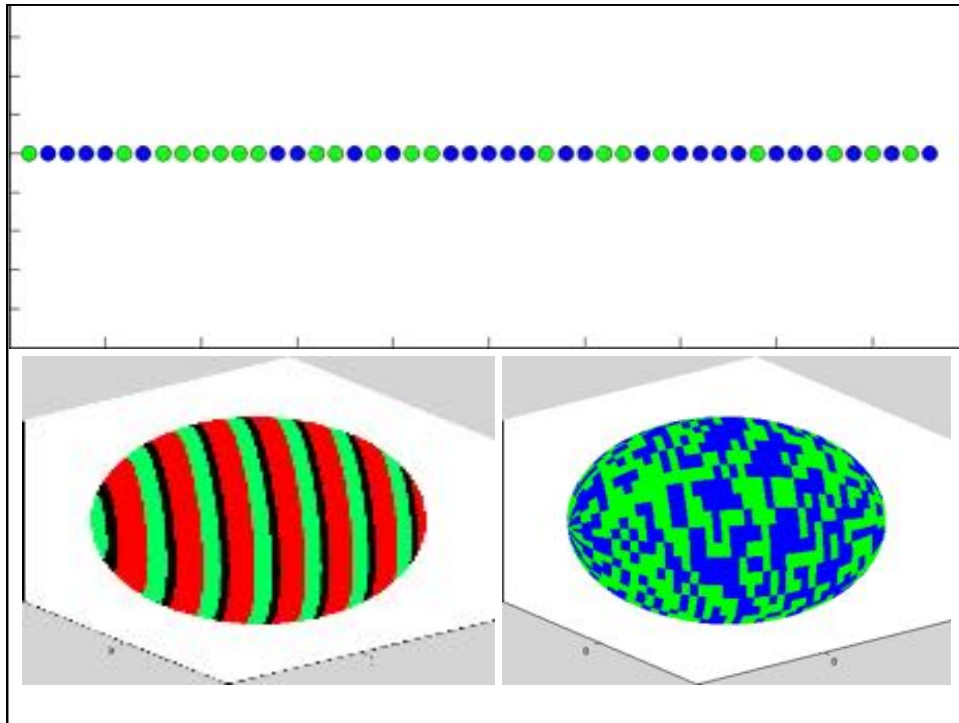
- $* \Rightarrow 0$
- $0* \Rightarrow 00$
- $00* \Rightarrow 000$
- $000* \Rightarrow 0001$

#### General cases

- $0001* \Rightarrow 00010$
- $0010* \Rightarrow 00100$
- $0100* \Rightarrow 01000$
- $1000* \Rightarrow 10001$

Example, try this initial condition: 1000 0010 0000 00000.....

In this case,  
You cannot do a left-side rule for  $r=2$   
Because  $00*$  is ambiguous  
 $00*$  could be 001 or 000



## Yamin's Global-to-Local Compiler

### Local Checkability-based Compiler

#### Input:

Target pattern, desired agent state and radius

#### Output:

Compiler tries to derive a local check scheme

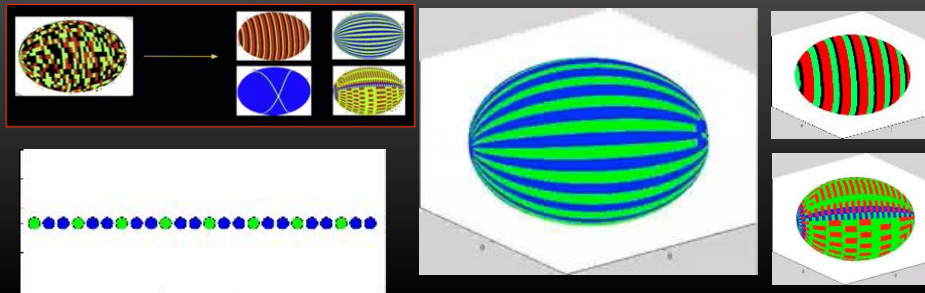
Either doesn't exist (suggest minimum radius needed)

Or Local Rule (scalable, asynchronous, self-repairing)

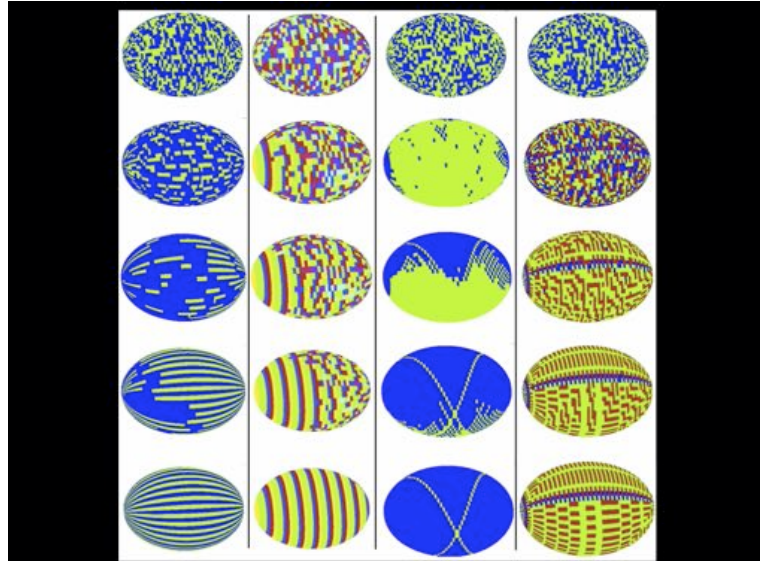
```

MATLAB 7.5.0 (R2007b)
File Edit Debug Desktop Window Help
Shortcuts [?] How to Add [?] What's New
>> T = Two_Ellipsoidal_Global_Compiler();
What pattern would you like? [1 2 0 0 0 0 3]
To form that pattern with 4 states you need a minimal radius of 3.
What is your maximum radius? 1
To form the pattern with radius 1 you need 4 extra state slots.
How long an ellipsoid do you want? 40
How wide an ellipsoid do you want? 40
A robust local rule solution to this pattern
has been written to the file 'local_rule.txt' and the
output variable contains a trajectory generated by the
rule on a randomly chosen initial condition.
>>
Start

```



## Compiler generated patterns

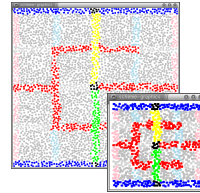
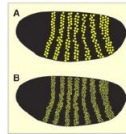
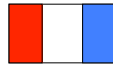


## Some Thoughts

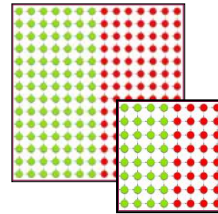
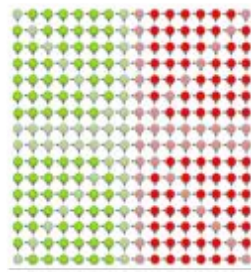
- So far we have tackled 1D systems. Can we generalize the ideas to other agent models?
- Open Questions:
  - More complex patterns
    - E.g. Majority vote (Melanie Mitchell)
  - More complex spaces
    - 3D cellular automata: *Lattice Swarms! (Th&B)*
  - Approximate (high-probability) solutions

## The Curious Case of 2D Proportional Patterns

Proportional Patterns are Interesting



In 1D (line), no solution exists with fixed state and radius  
But, in 2D (square), can solve with *finite* state and radius!



## Theoretical Underpinnings

- Reason *theoretically* about *intuitive* things
  - How one can tradeoff state and radius
  - Why some things are harder than others
  - Why some things take longer than others
  - How simple patterns can be combined to make complex ones
  - Why 1D patterns are like Strings (relation to grammars)
  - Why global-to-local is possible in CAs,  
whereas local-to-global may be so complex....