

Self-Reconfigurable “Cellular” Robots

CS289

Science Fiction



Science Fiction

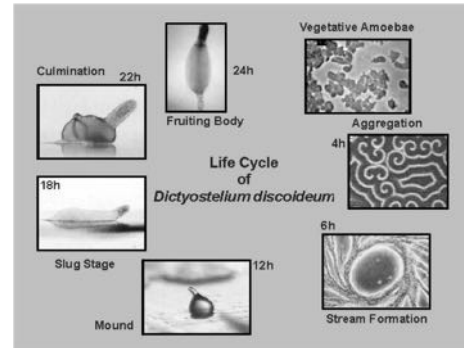


Science Fiction

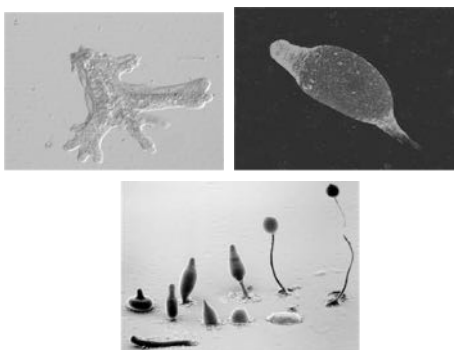


Reality
Stranger than Fiction?

Cellular Slime Mold



Cellular Slime Mold



Army Ants, Bridges & Bivouacs!



Daniel Kronauer, Rockefeller Univ.; Simon Garnier, NJIT; Scott Powell, G. Washington Univ

Reality to Robots....

Challenges

What is a necessary & sufficient individual “module” to create interesting “collective” robots.

– **Mechanical Design Challenge**

- Movement, attachment, power

– **Programming Challenge**

- Global-to-local, scalable, robust

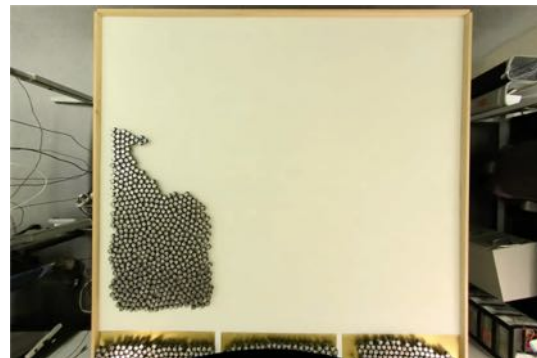
Both are closely linked.....

Mechanical Design Challenge

- Historical
 - CEBOT (Fakuda), Fracta (Murata)
- Chain-style Robots
 - Polybot, Superbot, Mtran (Yim, Shen, Murata/Kurokawa)
- Lattice-style Robots
 - E.g. ATRON (Ostergaard, Stoy)
- Stochastic Robots
 - Programmable Parts, Molecube (Klavins, Lipson)
- Programmable Materials
 - Pebbles (Rus) Claytronics (Goldstein)
- Applications:
 - From Space Exploration to Novel Displays!



Kilobots Self-Assembly



“Bucket of Stuff” metaphor

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Challenges

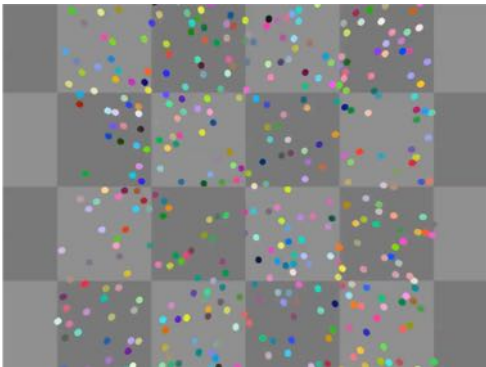
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Programming Challenge => Many Approaches

- **Mech**
 - Movement
 - **Program**
 - Global-to-local
1. Centralized Planning
 1. Find minimum number of steps to transform shape A to B.
 2. But, mostly NP hard and fragile
 2. Decentralized:
 1. Cellular Automata (ala Lindenmayer grammars, Rus et al)
 1. DevelBio-inspired (e.g. morphogen gradients, Shen et al)
 2. Chemistry-Inspired (“tiles” that stick to each other, Klavins et al)

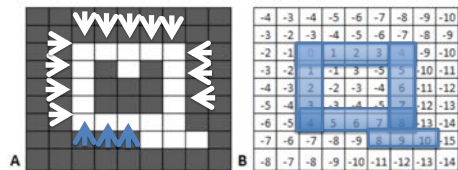
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S-DASH Algorithm



Discussions

The goal of the DASH algorithm is
 “programmable self-assembly with self-repair”
 – *What are the key elements of the DASH algorithm?*

**Key Idea:**

- The Gradient Map creates a “flow”
- Inside the object, flow “fills the container” bottom up.
- Outside the object, flow initially pushes into the empty object. Later, as object fills up, the flow pushes around and upwards

SDASH (later algorithm):

Added distributed coordinate formation, and “gossip” based scale belief.

Discussions

- What are the differences between:
 - DASH vs Biology (“French Flag” approach)
 - DASH vs Kilobots (Abstract->Physical)

Kilobots Self-Disassembly

Programmable self-disassembly for shape formation in large-scale robot collectives

Melvin Gauci, Radhika Nagpal, Michael Rubenstein
DARS 2016



Robots

