

- A field $(k, +, \times)$ is a set with two operations: $(k, +)$ abelian group with identity 0, $(k^* = k - \{0\}, \times)$ abelian group with identity 1; distributive law $a(b+c) = ab+ac$.

Lec. 6 Axler ch. 1 Examples: $\mathbb{Q}, \mathbb{R}, \mathbb{C}$ (characteristic 0: $\underbrace{1+\dots+1}_n = n \cdot 1 \neq 0$), $\mathbb{F}_p = \mathbb{Z}/p$ p prime (char. = p).

- A vector space over k is a set V with addition $+: V \times V \rightarrow V$ ($V, +$) abelian group, $0 \in V$ scalar mult. $k \times V \rightarrow V$ associative, distributive.

Ex: $k^n, k[x], \dots$ Subspace: $W \subset V$ closed under $+, \times$.

- $\text{span}(v_1, \dots, v_n) = \left\{ \sum a_i v_i \mid a_i \in k \right\} \subset V$, say (v_i) span V if $\text{span}(v_i) = V$.

Say (v_i) are linearly independent if $a_1 v_1 + \dots + a_n v_n = 0 \Rightarrow a_i = 0 \forall i$.

Basis = linearly independent vectors which span V : $k^n \rightarrow V$ isomorphism.
 $(a_i) \mapsto \sum a_i v_i$

- All bases of V have same cardinality = dim V

Any linearly independent set can be completed to a basis.

- $\text{Hom}(V, W) =$ linear maps $\varphi: V \rightarrow W$, $\varphi(u+v) = \varphi(u) + \varphi(v)$, $\varphi(\lambda u) = \lambda \varphi(u)$.
 This is a vector space.

- Given bases $(v_i)_{i=1..n}$ of V , $(w_j)_{j=1..m}$ of W , represent $v = \sum x_i v_i \in V$ by column $X = \begin{pmatrix} x_1 \\ \vdots \\ x_n \end{pmatrix}$ and $\varphi \in \text{Hom}(V, W)$ by matrix $A = (a_{ij})$ whose columns represent $\varphi(v_j)$ in basis (w_j) , $\varphi(v_i) = \sum a_{ij} w_j$. Then $\varphi(v)$ is represented in basis (w_j) by column vector $Y = AX$.

Change of basis: $P = (p_{ij}) = M(\text{id}, (v'_i), (v_i))$ ie. $v'_j = \sum p_{ij} v_i$, then for $\varphi: V \rightarrow V$, $M(\varphi, (v'_i)) = A' = P^{-1}AP$

$$\begin{array}{ccc} V & \xrightarrow{\varphi} & W \\ \text{basis } \uparrow \cong & & \uparrow \cong \text{basis} \\ k^n & \xrightarrow{A} & k^m \end{array}$$

- $V \cong W, \bigoplus \dots \bigoplus W_n$ direct sum decompt: if $\begin{cases} W_i \text{ span } V: \forall v \in V \exists w_i \in W_i \text{ st. } v = w_1 + \dots + w_n \\ W_i \text{ independent: } w_1 + \dots + w_n = 0, w_i \in W_i \Rightarrow w_i = 0 \forall i. \end{cases}$
 ie. $\varphi: \bigoplus W_i \rightarrow V$ is an isomorphism.

$$(w_i) \mapsto \sum w_i$$

- V finite dim. $\Rightarrow V = W_1 \oplus W_2$ iff $W_1 \cap W_2 = \{0\}$ and $\dim W_1 + \dim W_2 = \dim V$.

- dim/rank formula: V, W finite dim., $\varphi \in \text{Hom}(V, W) \Rightarrow \dim V = \dim \ker \varphi + \dim \text{Im } \varphi = \text{rank } \varphi$.

- \exists bases (v_i) of V , (w_j) of W st. $M(\varphi) = \begin{pmatrix} I_{r \times r} & 0 \\ 0 & 0 \end{pmatrix}_{\text{Ker } \varphi}^{\text{Im } \varphi}$

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- Dual: $V^* = \text{Hom}(V, k)$.

(e_i) basis of V (finite dim) \Rightarrow dual basis (e_i^*) of V^* st. $e_i^*(e_j) = \delta_{ij} = \begin{cases} 1 & i=j \\ 0 & \text{else.} \end{cases}$

$V \rightarrow V^{**}$
 $v \mapsto ev_v: (V \rightarrow k) \mapsto (l \mapsto l(v))$ is an isomorphism if $\dim V < \infty$ (injective if $\dim V = \infty$).

The annihilator of $U \subset V$ is $\text{Ann}(U) = \{l \in V^* \mid l(u) = 0 \forall u \in U\}$; $\dim \text{Ann}(U) = n - \dim U$.

The transpose of $\varphi \in \text{Hom}(V, W)$ is $\varphi^t: W^* \rightarrow V^*$, $\varphi^t(l) = l \circ \varphi$

$$\text{ker } \varphi^t = \text{Ann}(\text{Im } \varphi), \text{Im } \varphi^t = \text{Ann}(\text{ker } \varphi) \text{ if } \dim < \infty, M(\varphi^t, (f_j^*), (e_i^*)) = M(\varphi)^T$$

- Quotient: $U \subset V$ subspace $\Rightarrow V/U = \{\text{cosets } v+U\}$ is a vector space.

$V \xrightarrow{q} V/U$ is surjective with kernel $= U$.

$V \xrightarrow{\varphi} W$ factors through V/U
 $q \downarrow_{V/U} \exists \bar{\varphi}$ iff $U \subset \ker \varphi$.

Axler
ch. 5

- $W \subset V$ is an invariant subspace for $\varphi \in \text{Hom}(V, V)$ if $\varphi(W) \subset W$.

Ex. $\ker(\varphi)$, $\text{Im}(\varphi)$; eigenpaces $\ker(\varphi - \lambda I)$.

- if $V = \bigoplus V_i$, V_i invariant for $\varphi \Rightarrow \exists$ basis where $M(\varphi) = \text{block diagonal} \begin{pmatrix} \varphi|_{V_1} & 0 \\ 0 & \varphi|_{V_2} \end{pmatrix}$
 A basis of eigenvectors $v_i \in V$, $v_i \neq 0$, $\varphi(v_i) = \lambda_i v_i \Leftrightarrow \varphi$ diagonalizable $M(\varphi, (v_i)) = \begin{pmatrix} \lambda_1 & 0 \\ 0 & \lambda_n \end{pmatrix}$.

- Eigenvectors of φ for distinct eigenvalues are linearly indept

- If k is algebraically closed (e.g. C) then any linear op. $\varphi \in \text{Hom}(V, V)$ has an eigenvector.

Conclay: \exists basis in which $M(\varphi)$ is upper triangular $\begin{pmatrix} * & * & * \\ 0 & * & * \\ 0 & 0 & * \end{pmatrix}$

$\lambda \in k$ is an eigenvalue of $\varphi \Leftrightarrow (\varphi - \lambda)$ not invertible $\Leftrightarrow \lambda$ appears on diagonal in a triangular matrix representing φ .

- The generalized kernel $g\ker(\varphi) = \ker(\varphi^N) \forall N$ large (e.g. $\geq \dim V$).

φ is nilpotent if $\varphi^N = 0$; $\ker(\varphi) \subset \ker(\varphi^2) \subset \dots$ \exists basis st. $M(\varphi)$ block diagonal with blocks $\begin{pmatrix} 0 & 1 & 0 \\ 0 & \ddots & 1 \\ 0 & 0 & 0 \end{pmatrix}$

- generalized eigenspaces $V_\lambda = g\ker(\varphi - \lambda) = \ker(\varphi - \lambda)^N$ are linearly independent invariant subspaces.

- if k is alg. closed then $V = \text{direct sum } \bigoplus V_\lambda$ of the gen't eigenspaces of φ .

This gives the Jordan normal form: $M(\varphi)$ block diagonal with blocks $\begin{pmatrix} \lambda & 1 & 0 \\ 0 & \ddots & 1 \\ 0 & 0 & \lambda \end{pmatrix}$

(φ diagonalizable \Leftrightarrow all blocks have size 1).

Lec. 11

- characteristic polynomial of φ : $\chi_\varphi(x) = \det(xI - \varphi) = \prod_{\lambda_i} (x - \lambda_i)^{n_i}$, $n_i = \text{mult}(\lambda_i) = \dim V_{\lambda_i}$.
 minimal polynomial: $\mu_\varphi(x) = \prod (x - \lambda_i)^{m_i}$, $m_i = \min \{m \mid V_{\lambda_i} = \ker(\varphi - \lambda_i)^m\} = \text{size of largest Jordan block in } V_{\lambda_i}$.
- $P(\varphi) = 0$ iff $\mu_\varphi \mid P(x)$. In particular $\mu_\varphi \mid \chi_\varphi$.
 φ diagonalizable $\Leftrightarrow m_i = 1 \forall i$.

- Over \mathbb{R} , $\varphi: V \rightarrow V$ need not have eigenvectors, but by considering $V_C = V \times V = \{v+iw \mid v, w \in V\}$ and $\varphi_C: V_C \rightarrow V_C$, $\varphi_C(v+iw) = (\varphi(v)+i\varphi(w)) \Rightarrow$ any real operator has an invariant subspace of dimension 1 (eigenvector!) or 2.

Axler
ch 9A

- Categories have objects, and morphisms $\text{Mor}(A, B)$ $\forall A, B \in \text{ob } \mathcal{C}$, with operation = composition.
 Axioms: $\forall A \in \text{ob } \mathcal{C}$, $\exists id_A \in \text{Mor}(A, A)$, $f \circ id_A = id_B \circ f = f$; associativity $(f \circ g) \circ h = f \circ (g \circ h)$.

Ex: sets, groups, vector spaces/k

Lec. 12

- A functor $F: \mathcal{C} \rightarrow \mathcal{D}$ assigns
 - to each $X \in \text{ob } \mathcal{C}$, $F(X) \in \text{ob } \mathcal{D}$
 - to $f \in \text{Mor}_{\mathcal{C}}(X, Y)$, $F(f) \in \text{Mor}_{\mathcal{D}}(F(X), F(Y))$
 st. $F(id_X) = id_{F(X)}$ and $F(g \circ f) = F(g) \circ F(f)$. (contravariant functors = reverse dir. of morphisms)
- Natural transformation t between functors $F, G: \mathcal{C} \rightarrow \mathcal{D}$
 - for each $X \in \text{ob } \mathcal{C}$, $t_X \in \text{Mor}_{\mathcal{D}}(F(X), G(X))$ st. $\begin{array}{ccc} X & \xrightarrow{F(X)} & G(X) \\ \downarrow f & & \downarrow G(f) \\ Y & \xrightarrow{F(Y)} & G(Y) \end{array}$ commutes.

Axler ch6 • A bilinear form on V is $b: V \times V \rightarrow k$, linear in each input $b(u+v, w) = b(u, w) + b(v, w)$ (3)
Lec. 12 b is symmetric if $b(u, v) = b(v, u)$, skew-symmetric if $b(u, v) = -b(v, u)$.
 $b(\lambda u, v) = \lambda b(u, v)$ etc.

- $B(V) = \{ \text{bilinear } b: V \times V \rightarrow k \} \xrightarrow{\sim} \text{Hom}(V, V^*)$ (isom. of vector spaces)

$$b \mapsto \varphi_b: V \xrightarrow{\sim} (b(v, \cdot): V \rightarrow k)$$

$\text{rank}(b) = \text{rank}(\varphi_b)$, b is nondegenerate if $\varphi_b: V \xrightarrow{\sim} V^*$ isomorphism.

- in a basis (e_i) of V , b is represented by a matrix $B = (b_{ij}) = (b(e_i, e_j))$.

if $u = \sum x_i e_i$, $v = \sum y_j e_j$ are represented by column vectors X, Y , $b(u, v) = X^T B Y$.

- the orthogonal of $S \subset V$ for b is $S^\perp = \{v \in V / b(v, w) = 0 \ \forall w \in S\} = \text{Ker}(V \rightarrow S^*)$

If b is nondegenerate then $\dim S^\perp = \dim V - \dim S$

$$v \mapsto \varphi_b(v)/S$$

If b is an inner product then $S \cap S^\perp = \{0\}$ and $V = S \oplus S^\perp$.

- A real inner product $\langle \cdot, \cdot \rangle: V \times V \rightarrow \mathbb{R}$ is a symmetric definite positive bilinear form.

Cauchy-Schwarz ineq: $\langle u, v \rangle \leq \|u\| \|v\|$. $\hookrightarrow \langle u, u \rangle = \|u\|^2 \geq 0 \ \forall u \neq 0$.

Over \mathbb{C} , we consider Hermitian inner products $\langle \cdot, \cdot \rangle: V \times V \rightarrow \mathbb{C}$, not quite bilinear: $\langle \lambda u, v \rangle = \bar{\lambda} \langle u, v \rangle$ require Hermitian-symmetric $\langle u, v \rangle = \overline{\langle v, u \rangle}$, and definite positive $\langle u, u \rangle = \|u\|^2 \geq 0 \ \forall u \neq 0$.

The map $V \rightarrow V^*$ induced by such $\langle \cdot, \cdot \rangle$ is \mathbb{C} -antilinear: $\varphi(\lambda u) = \bar{\lambda} \varphi(u)$.

- Every finite dimensional inner product space (over \mathbb{R} or \mathbb{C}) has an orthonormal basis (e_1, \dots, e_n) st. $\langle e_i, e_j \rangle = \delta_{ij}$. (build by induction e.g. using Gram-Schmidt).

Axler ch. 7 • Let $V, \langle \cdot, \cdot \rangle$ inner product space (over \mathbb{R} or \mathbb{C}), $T: V \rightarrow V$ linear operator.
The adjoint operator $T^*: V \rightarrow V$ satisfies $\langle v, Tw \rangle = \langle T^*v, w \rangle \ \forall v, w \in V$.
(Corresponds to the transpose of T via $V \xrightarrow{\varphi} V^*$; over \mathbb{C} : complex conjugate of T^t).
In an orthonormal basis, $M(T^*) = M(T)^t$ (real case) or $\overline{M(T)}^t$ (complex Hermitian case)
 $\text{Ker}(T^*) = \text{Im}(T)^\perp$ and vice-versa.

- $T: V \rightarrow V$ is self-adjoint if $T^* = T$

T is orthogonal (unitary over \mathbb{C}) if $T^* = T^{-1}$, i.e. $\langle Tu, Tv \rangle = \langle u, v \rangle \ \forall u, v \in V$.

($\Leftrightarrow T$ maps orthonormal basis to orthonormal basis)

- If $S \subset V$ is invariant under a self-adjoint/orthogonal/unitary operator then so is S^\perp .
 \Rightarrow spectral theorem (real and complex versions):

• If $T: V \rightarrow V$ is self-adjoint then T is diagonalizable, with real eigenvalues, and can be diagonalized in an orthonormal basis.

• If $T: V \rightarrow V$ is orthogonal for a real inner product, then V is a direct sum of orthogonal invariant subspaces of dim 1 or 2, with T acting by ± 1 on the 1-dim¹ pieces rotations on 2-dim¹ pieces.

• If $T: V \rightarrow V$ is unitary for a Hermitian inner product, then

T is diagonalizable in an orthonormal basis, with eigenvalues $|\lambda_i| = 1$.

Lec. 14

Lec. 15

- Besides inner products, one can also consider arbitrary nondegenerate symmetric bilinear forms (without assuming positivity); eg. over \mathbb{R} (resp. \mathbb{C}), \exists orthogonal basis st.

Lec. 16 $b(e_i, e_j) = \begin{cases} \pm 1 & i=j \\ 0 & i \neq j \end{cases}$ (resp. $b(e_i, e_j) = \delta_{ij}$); or skew-symmetric bilinear forms.

Handout • Tensor product: $V \otimes W$ vector space, with a bilinear map $V \times W \xrightarrow{\quad b \quad} V \otimes W$, st. $(v, w) \mapsto v \otimes w$

bilinear maps $V \times W \xrightarrow{b} U$ correspond to linear maps $V \otimes W \xrightarrow{\varphi} U$ ($\varphi(v \otimes w) = b(v, w)$)

Elements of $V \otimes W$ are finite linear combinations $\sum v_i \otimes w_i$.

If (e_i) basis of V and (f_j) basis of W , then $(e_i \otimes f_j)$ basis of $V \otimes W$.

- $V^* \otimes W \cong \text{Hom}(V, W)$, by mapping $l \otimes w \in V^* \otimes W$ to $(v \mapsto l(v)w) \in \text{Hom}(V, W)$.

- the trace $\text{tr}(T: V \rightarrow V) = \sum \lambda_i \in k$ can be defined by $\text{Hom}(V, V) \cong V^* \otimes V \rightarrow k$ $l \otimes v \mapsto l(v)$

- Lec. 17 • multilinear maps $V_1 \times \dots \times V_n \rightarrow U \Leftrightarrow$ linear maps $V_1 \otimes \dots \otimes V_n \rightarrow U$.

- $V^{\otimes n} = V \otimes \dots \otimes V$ contains subspaces

$\text{Sym}^n(V) =$ symmetric tensors (\Leftrightarrow symmetric multilinear maps) $v_{\sigma(1)} \dots v_{\sigma(n)} = v_1 \dots v_n$

$\Lambda^n(V) =$ exterior powers: alternating tensors $v_{\sigma(1)} \wedge \dots \wedge v_{\sigma(n)} = (-1)^{\sigma} v_1 \wedge \dots \wedge v_n$.

- if $\dim V = n$ then $\Lambda^n V$ has dim 1; for $T: V \rightarrow V$, $\Lambda^n T: \Lambda^n V \rightarrow \Lambda^n V$ is multiplication by a scalar, the determinant $\det(T) \in k$.

- The theory of modules over a ring $(R, +, \cdot)$ (elements need not have multiplicative inverses) is more complicated than that of vector spaces.

Finitely generated modules need not have a basis; those that do are called free.

- \mathbb{Z} -modules \Leftrightarrow abelian groups.

Lec. 19 Every finitely generated \mathbb{Z} -module M with generators (e_1, \dots, e_n) is a quotient of \mathbb{Z}^n

(parts of Artin ch. 14) $(\varphi: \mathbb{Z}^n \rightarrow M \quad (a_i) \mapsto \sum a_i e_i)$ and $\ker(\varphi) \subset \mathbb{Z}^n$ is itself a free module, ie. $\exists T: \mathbb{Z}^m \rightarrow \mathbb{Z}^n$ st. $M \cong \mathbb{Z}^n / \text{Im } T$

\rightarrow via linear algebra over \mathbb{Z} , one finds:

Every finitely generated abelian group is $\cong \mathbb{Z}^r \times \mathbb{Z}/n_1 \times \dots \times \mathbb{Z}/n_k$ for some r, n_1, \dots, n_k .