

* Recall | a field $(k, +, \times)$ = set with two operations, $(k, +)$ abelian group with identity 0, $(k^* = k - \{0\}, \times)$ abelian group with identity 1, distributive law.

* Polynomials: $k[x] := \{a_0 + a_1 x + \dots + a_n x^n \mid a_i \in k, n \in \mathbb{N}\}$ is a ring \rightsquigarrow field of fractions = field of rational functions

$$k(x) = \left\{ \frac{p}{q} \mid p, q \in k[x], q \neq 0 \right\} / \frac{p}{q} \sim \frac{p'}{q'}, \text{ iff } pq' = qp'.$$

(This generalizes to polynomials & rational functions in any number of variables)

* Power series: || The ring of formal power series in x is $k[[x]] = \left\{ \sum_{i=0}^{\infty} a_i x^i \mid a_i \in k \right\}$
 (add and multiply just like polynomials, term by term.
 check each coefficient in $(\sum a_i x^i)(\sum b_j x^j)$ is a finite expression).

Lemma: || $\sum a_i x^i$ has a multiplicative inverse in $k[[x]]$ iff $a_0 \neq 0$.

Proof: We want $\sum b_i x^i$ st. $(\sum a_i x^i)(\sum b_i x^i) = 1$. This gives

$$\left. \begin{array}{l} a_0 b_0 = 1 \\ a_0 b_1 + a_1 b_0 = 0 \\ a_0 b_2 + a_1 b_1 + a_2 b_0 = 0 \\ \dots \end{array} \right\} \rightarrow \text{if } a_0 = 0, \text{ clearly no solution; if } a_0 \neq 0, \text{ we can solve inductively: } b_0 = \frac{1}{a_0}, b_1 = -\frac{a_1 b_0}{a_0}, \dots \text{ (each step is } b_i = -(\dots)/a_0 \text{ ✓). } \quad \square$$

→ since every nonzero element of $k[[x]]$ is of the form

$\overbrace{a_m x^m + a_{m+1} x^{m+1} + \dots}^{\text{first nonzero coefficient}} = x^m \underbrace{(a_m + a_{m+1} x + \dots)}_{\text{invertible}}$, to get a field we just need to allow x^{-m} .

→ Def: || The field of Laurent series $k((x)) = \left\{ \sum_{i=m}^{\infty} a_i x^i \mid m \in \mathbb{Z}, a_i \in k \right\}$.

* Given a field k , and a polynomial $f \in k[x]$ (of degree > 0), we can evaluate $f(r)$, $r \in k$, and look for roots $r \in k$ st. $f(r) = 0$.

If there are none in k , we can form a field $K \supset k$ in which f has a root.

Ex: $k = \mathbb{Q}$, $x^2 - 2$ has no roots, but we can form

$$\mathbb{Q}(\sqrt{2}) := \{a + b\sqrt{2} \mid a, b \in \mathbb{Q}\} \text{ which is a field: } \frac{1}{a+b\sqrt{2}} = \frac{a-b\sqrt{2}}{a^2-2b^2} \in \mathbb{Q}(\sqrt{2})$$

Ex: $k = \mathbb{R}$, $x^2 + 1 \rightsquigarrow \mathbb{R}(\sqrt{-1}) = \mathbb{C}$. \rightarrow usually called i .

→ On the other hand, over an algebraically closed field such as \mathbb{C} , every nonconstant polynomial already has a root, and there are no further algebraic extensions

(2)

* Given a field k , we always have a ring homomorphism $\varphi: \mathbb{Z} \rightarrow k$
 (this determines φ , since 1 generates \mathbb{Z}) $\hookrightarrow \begin{matrix} 1 \mapsto 1_k \\ \varphi(a+b) = \varphi(a) + \varphi(b), \quad \varphi(ab) = \varphi(a)\varphi(b) \end{matrix}$

Is this injective? For most fields we'll consider (e.g. $\mathbb{Q}, \mathbb{R}, \mathbb{C}, \mathbb{R}(x), \mathbb{R}((x))$, ...), it is.
 If so, say k has characteristic zero. Otherwise:

Prop: $\ker(\varphi: \mathbb{Z} \rightarrow k) = \mathbb{Z}_p$ for some prime p .

Pf: $\ker(\varphi)$ is a subgroup of \mathbb{Z} , hence of the form \mathbb{Z}_n . If n is not prime, write $n = ab$ for $1 < a, b < n$. Then $\varphi(n) = \varphi(ab) = \varphi(a)\varphi(b) = 0 \in k$, but this implies $\varphi(a) = 0$ or $\varphi(b) = 0$ (if $\varphi(a) \neq 0$, multiply by $\varphi(a)^{-1}$ to get $\varphi(b) = 0$). Since by assumption n is the smallest positive integer s.t. $\varphi(n) = 0$, this is a contradiction. \square

Def: Say k has characteristic p if $\ker(\varphi) = \mathbb{Z}_p$. (This means $p \cdot 1_k = \underbrace{1 + \dots + 1}_{p \text{ times}} = 0!$)

So far our only example of such a field is \mathbb{Z}/p , but there are more.

Theorem: For all $n \geq 1$ and prime p , there exists a unique field with p^n elements (up to isomorphism), and these are all the finite fields.

(There are also infinite fields of characteristic p , for example $\mathbb{Z}/p((x))$!).

Vector spaces:

Def: fix a field k . A vector space over k is a set V with two operations:

(1) addition $+: V \times V \rightarrow V$

(2) scalar multiplication $\cdot: k \times V \rightarrow V$

such that (1) $(V, +)$ is an abelian group (denote by 0 the identity element)

(2) $1v = v \quad \forall v \in V$

(3) $(ab)v = a(bv) \quad \forall a, b \in k, \forall v \in V$

(4) $(a+b)v = av + bv \quad \forall a, b \in k, \forall v \in V$

(5) $a(v+w) = av + aw \quad \forall a \in k, \forall v, w \in V$

} identity and
associativity for \cdot

} distributive
property

(Note: $0v = 0 \quad \forall v \in V$ using distributive property).

Def: A subspace of a vector space is a nonempty subset $W \subset V$ that is preserved by addition and scalar multiplication: $W + W \subset W, k \cdot W \subset W$.

(so W is also a vector space!)

\uparrow in fact $= W$ \hookrightarrow this implies $0 \in W$.

Examples: • $k^n = \{(a_1, \dots, a_n) \mid a_i \in k\}$ with componentwise addition / scalar mult.

• $k^\infty = \{(a_i)_{i \in \mathbb{N}} \mid a_i \in k\}$ (sequences in k) $\supset \{\text{sequences which are eventually zero}\}$

- $k[[x]] \supset k[x]$ (isomorphic to the previous example!)

- given any set S , $k^S = \{ \text{maps } f: S \rightarrow k \}$ ($k^\infty \Leftrightarrow \text{case } S = \mathbb{N}$)
- $\{\text{maps } \mathbb{R} \rightarrow \mathbb{R}\} \supset \{\text{continuous maps}\} \supset \{\text{differentiable maps } \mathbb{R} \rightarrow \mathbb{R}\}$

Span, linear independence, basis: let V be a vector space $/k$.

Def: Given $v_1, \dots, v_n \in V$, the span of v_1, \dots, v_n is the smallest subspace of V which contains v_1, \dots, v_n . Concretely, $\text{span}(v_1, \dots, v_n) = \{a_1v_1 + \dots + a_nv_n \mid a_i \in k\}$

Def: say v_1, \dots, v_n span V if $\text{span}(v_1, \dots, v_n) = V$.

Def: We say $v_1, \dots, v_n \in V$ are linearly independent if $a_1v_1 + \dots + a_nv_n = 0 \Rightarrow a_1 = a_2 = \dots = a_n = 0$.

Equivalently, given $v_1, \dots, v_n \in V$, we have a linear map $\phi: k^n \rightarrow V$
 v_1, \dots, v_n are linearly indept $\Leftrightarrow \phi$ injective
 v_1, \dots, v_n span $V \Leftrightarrow \phi$ surjective.

Def: (v_1, \dots, v_n) are a basis of V if they are linearly independent and span V .

Then any element of V can be expressed uniquely as $\sum a_i v_i$ for some $a_i \in k$.

Ex: $(1, 0)$ and $(0, 1)$ are a basis of k^2 . So are $(1, 1)$ and $(1, -1)$ for most fields k . (what if $\text{char}(k) = 2$?)

* We will see soon: if V has a basis with n elements, then every basis of V has n elements. We say the dimension of V is $\dim(V) = n$.

One can also consider infinite-dimensional vector spaces: for $S \subset V$ any subset,

Def:

- $\text{span}(S) = \text{smallest subspace of } V \text{ containing } S$
 $= \{a_1v_1 + \dots + a_kv_k \mid k \in \mathbb{N}, a_i \in k, v_i \in S\}$
 $\quad (\text{all finite linear combinations of elements of } S)$
- The elements of S are linearly independent if there are no finite linear relations:
 $a_1v_1 + \dots + a_kv_k = 0 \quad (a_i \in k, v_i \in S) \Rightarrow a_1 = \dots = a_k = 0$.
- S is a basis of V if its elements are linearly indept and span V .

Example: $\{1, x, x^2, x^3, \dots\}$ is a basis of $k[x]$.

• does $k[[x]]$ have a basis? what is it?

Linear maps:

Def. Let V, W be vector spaces/k. A homomorphism of vector spaces, or linear map, $\varphi: V \rightarrow W$, is any map that is compatible with the operations:
 $\varphi(u+v) = \varphi(u) + \varphi(v)$, $\varphi(\lambda v) = \lambda\varphi(v) \quad \forall \lambda \in k, \forall u, v \in V$.

Prop: || The set of linear maps $V \rightarrow W$ is itself a vector space/k, denoted $\text{Hom}(V, W)$.

Proof: Given $\varphi, \psi \in \text{Hom}(V, W)$, define $\begin{cases} \varphi + \psi \text{ by } (\varphi + \psi)(v) = \varphi(v) + \psi(v), \forall v \in V \\ \lambda\varphi \text{ by } (\lambda\varphi)(v) = \lambda \cdot \varphi(v) \end{cases}$

One can check that • $\varphi + \psi$ and $\lambda\varphi$ defined in this way are linear maps
(rather boring, but worth checking if you're not sure!) • these operations on $\text{Hom}(V, W)$ satisfy the axioms of a vector space. \square

- We'll soon see: if $\dim(V) = n$ and $\dim(W) = m$ then $\dim(\text{Hom}(V, W)) = mn$. (in bases for V and W , linear maps become $m \times n$ matrices!)

* How does the choice of the field k matter when discussing vector spaces?

Given a subfield $k' \subset k$ (eg. $\mathbb{R} \subset \mathbb{C}$ or $\mathbb{Q} \subset \mathbb{R}$), a vector space over k can also be viewed as a vector space over k' , by "restriction of scalars".

(namely, only look at scalar multiplication restricted to domain $k' \times V \subset k \times V$)

In particular, k itself is a vector space over k' !

Ex: \mathbb{C} is a vector space over itself (of dim. 1, $\{1\}$ is a basis)

It is also a vector space over \mathbb{R} (of dim. 2, with basis $\{1, i\}$)

If V, W are \mathbb{C} -vector spaces hence also \mathbb{R} -vector spaces,

any \mathbb{C} -linear map is also \mathbb{R} -linear, but the converse isn't true: $\text{Hom}_{\mathbb{C}}(V, W) \subsetneq \text{Hom}_{\mathbb{R}}(V, W)$

For example, complex conjugation $\mathbb{C} \xrightarrow{\quad} \mathbb{C}$ is \mathbb{R} -linear: $\begin{cases} \bar{z_1 + z_2} = \bar{z}_1 + \bar{z}_2 \\ \bar{az} = a\bar{z} \quad \forall a \in \mathbb{R} \end{cases}$

So: the choice of field k matters.

Bases and dimension:

- * Say V is finite-dimensional if there is a finite subset $\{v_1, \dots, v_m\}$ which spans V , ie. all elts of V are linear combinations $\sum a_i v_i$.
- * Lemma: || if $\{v_1, \dots, v_m\}$ spans V , then a subset of $\{v_1, \dots, v_m\}$ is a basis.

Proof: If the $\{v_i\}$ are linearly independent, they form a basis.

Otherwise, there is some linear relation $\sum a_i v_i = 0$, a_i not all zero.

but not \mathbb{C} -linear ($i\bar{z} \neq \bar{i}\bar{z}$).

This can be solved for v_i = a linear combination of the others if $a_i \neq 0$. (5)

→ remove v_i , $\{v_j / j \neq i\}$ still spans V .

Continue removing elements until the remaining ones are linearly indep! □

* Thus, every finite-dimensional vector space has a basis.

* Lemma: || If $\{v_1, \dots, v_m\}$ are linearly indep!, there exists a basis of V which contains $\{v_1, \dots, v_m\}$

Proof: Let $\{w_1, \dots, w_r\}$ be a spanning set for V , by induction we enlarge $\{v_1, \dots, v_m\}$ to a basis of $W_j = \text{span}(\{v_1, \dots, v_m, w_1, \dots, w_j\}) \subset V$ for each $j=0, \dots, r$. For $j=0$: $\{v_1, \dots, v_m\}$ basis of W_0 .

Assuming $\{v_1, \dots, v_m, w_1, \dots, w_{j-1}\}$ is a basis of $W_{j-1} = \text{span}(\{v_1, \dots, v_m, w_1, \dots, w_{j-1}\})$, if $w_j \in W_{j-1}$ then we already have a basis of $W_j = W_{j-1}$.

otherwise, $\{v_1, \dots, v_m, w_1, \dots, w_{j-1}, w_j\}$ are linearly indep! (why?) and span W_j .

This ends with a basis of $W_r = V$ (since $\{w_1, \dots, w_r\}$ span). □

* Theorem: || If $\{v_1, \dots, v_m\}$ and $\{w_1, \dots, w_n\}$ are bases of V , then $m=n$. (same # elements)

Prof: • We claim $\exists j \in \{1 \dots n\}$ st. $\{v_1, \dots, v_{m-1}, w_j\}$ is a basis.

Indeed, $\{v_1, \dots, v_{m-1}\}$ are linearly independent, but don't span V

(else $v_m \in \text{span}(\{v_1, \dots, v_{m-1}\})$ gives a linear relation $\sum_{i=1}^{m-1} a_i v_i - v_m = 0$)

So $\exists j$ st. $w_j \notin \text{span}(\{v_1, \dots, v_{m-1}\})$ (else w_1, \dots, w_n can't span all V).

Now $\{v_1, \dots, v_{m-1}, w_j\}$ are linearly independent (why?),

but using all the v 's, can write $w_j = \sum_{i=1}^m a_i v_i$ (necess. $a_m \neq 0$)

So $v_m = \frac{1}{a_m} (w_j - \sum_{i=1}^{m-1} a_i v_i) \in \text{span}(\{v_1, \dots, v_{m-1}, w_j\})$

and this implies $\{v_1, \dots, v_{m-1}, w_j\}$ span V hence are a basis.

• Repeat this process to exchange one v for one w each time

(we don't use the same w twice since the new w we pick has to be independent of the rest of our basis)

We end up with only w 's & get an m -element subset of $\{w_1, \dots, w_n\}$ that is also a basis. Necessarily this is all of $\{w_1, \dots, w_n\}$, and $m=n$. □

* Def: || The dimension of V is the cardinality of any basis.