

Recall: • $V^{\otimes d}$ = vector space gen^d by pure tensors $v_1 \otimes \dots \otimes v_d$, $v_i \in V$
 tensor power with relations so that $V \times \dots \times V \xrightarrow{\mu} V^{\otimes d}$ is multilinear
 $(v_1, \dots, v_d) \mapsto v_1 \otimes \dots \otimes v_d$
 (+ multilinear maps $V \times \dots \times V \rightarrow U \iff$ linear maps $V^{\otimes d} \rightarrow U$
 $m = \varphi \circ \mu$)

+ $\text{Sym}^d V$ same for symmetric multilinear maps.

Exterior algebra: do the same thing for skew-symmetric, aka alternating, multilinear forms.

Def: $\eta \in V^{\otimes d}$ is alternating if $\sigma(\eta) = (-1)^\sigma \eta \quad \forall \sigma \in S_d$.
 $\Lambda^d(V) = \{\text{alternating tensors}\} \subset V^{\otimes d}$.
 ↑ sign of σ : -1 for transpositions & products of odd # of them.

• In characteristic zero, we can view $\Lambda^d(V)$ as the image of skew-symmetrization operator $\beta: V^{\otimes d} \rightarrow V^{\otimes d}$

$$\beta(v_1 \otimes \dots \otimes v_d) = \frac{1}{d!} \sum_{\sigma \in S_d} (-1)^\sigma v_{\sigma(1)} \otimes \dots \otimes v_{\sigma(d)} \stackrel{\text{def: notation:}}{=} v_1 \wedge \dots \wedge v_d$$

This is zero whenever $v_i = v_j$ for some $i \neq j$ and so by multilinearity, whenever v_1, \dots, v_d are linearly dependent. Thus $\Lambda^d(V) = 0$ whenever $d > \dim V$!

• Alternative definitions $\Lambda^d(V) =$ quotient of $V^{\otimes d}$ by the subspace spanned by $v_1 \otimes v_2 \otimes v_3 \otimes \dots \otimes v_d + v_2 \otimes v_1 \otimes v_3 \otimes \dots \otimes v_d$ and similarly for other transpositions swapping two factors

Or: $\Lambda^d(V)$ vector space with an alternating multilinear map $V \times \dots \times V \rightarrow \Lambda^d V$
 $(v_1, \dots, v_d) \mapsto v_1 \wedge \dots \wedge v_d \quad (v_1 \wedge v_2 = -v_2 \wedge v_1 \text{ etc.})$

and universal for alternating multilinear maps on $V \times \dots \times V$.

- If (e_1, \dots, e_n) are a basis of V then $e_{i_1} \wedge \dots \wedge e_{i_d}$, $i_1 < \dots < i_d$ basis of $\Lambda^d V$.
- We have a product $\Lambda^k V \otimes \Lambda^l V \rightarrow \Lambda^{k+l} V$ induced by Tensor algebra + skew-symmetrization. $(v_1 \wedge \dots \wedge v_k) \wedge (w_1 \wedge \dots \wedge w_l) = v_1 \wedge \dots \wedge v_k \wedge w_1 \wedge \dots \wedge w_l$.

This makes the exterior algebra $\Lambda^\bullet V = \bigoplus_{d \geq 0} \Lambda^d V$ into a (skew-commutative) ring

ie. if $\eta \in \Lambda^k V$, $\xi \in \Lambda^l V$ then $\eta \wedge \xi = (-1)^{kl} \xi \wedge \eta$.

(check: $\dim \Lambda^\bullet V = 2^{\dim V}$).

Volume & determinant,

(2)

• If $\dim V = n$, then $\dim \Lambda^n V = 1$ (if e_1, \dots, e_n basis of $V \rightarrow e_1 \wedge \dots \wedge e_n \in \Lambda^n V$)

A choice of isomorphism $\Lambda^n V \xrightarrow{\sim} k$ is determined by the data of a volume form $\text{vol} \in \Lambda^n V^* = (\Lambda^n V)^*$, $\text{vol} \neq 0$, i.e. a nondegenerate alternating multilinear map $V \times \dots \times V \rightarrow k$
 $v_1, \dots, v_n \mapsto \text{vol}(v_1, \dots, v_n)$

(Think of: signed volume of parallelepiped with edge vectors v_1, \dots, v_n is naturally $v_1 \wedge \dots \wedge v_n \in \Lambda^n V$, becomes a scalar given $\Lambda^n V \xrightarrow{\sim} k$).

• Eg, in a real inner product space with orthonormal basis (e_1, \dots, e_n) ,

the natural volume form is $\text{vol} = e_1^* \wedge \dots \wedge e_n^*$, so $\text{vol}(e_1, \dots, e_n) = 1$. (reordering basis gives ± 1 ... orientation!)

(Volume of unit cube is 1). Using basis to identify $V \simeq \mathbb{R}^n$,

$$\begin{aligned} \text{vol}(v_1, \dots, v_n) &= (e_1^* \wedge \dots \wedge e_n^*)(v_1, \dots, v_n) = \sum_{\sigma \in S_n} (-1)^\sigma (e_{\sigma(1)}^* \otimes \dots \otimes e_{\sigma(n)}^*)(v_1, \dots, v_n) \\ v_j &= \begin{pmatrix} v_{1j} \\ \vdots \\ v_{nj} \end{pmatrix} \text{ for each } j &= \sum_{\sigma \in S_n} (-1)^\sigma v_{\sigma(1)1} \dots v_{\sigma(n)n} = \det(v_1, \dots, v_n) \end{aligned}$$

the determinant of an $n \times n$ matrix!

Recall that the determinant of a matrix is $\det(A) = \sum_{\sigma \in S_n} (-1)^\sigma \prod a_{\sigma(j)j}$.

$\det(A)$ is the only quantity which is $\left\{ \begin{array}{l} \bullet \text{ multilinear in the columns of the matrix} \\ \bullet \text{ alternating (swap two columns} \rightarrow -\det) \\ \bullet \det(\text{Id}) = 1. \end{array} \right.$

• Even though the notion of determinant / volume of $n = \dim V$ vectors requires a choice of volume form (isom. $\Lambda^n V \xrightarrow{\sim} k$) the notion of determinant of a linear operator requires no such choice!

→ Usual definition: given $T: V \rightarrow V$, define $\det(T) = \det(A)$, $A = \mathcal{M}(T)$ in any basis, using $\det(AB) = \det A \det B$, so under change of basis, $\det(P^{-1}AP) = \det A$.
↳ usual proof is painfully explicit.

→ Better definition: exterior power is a functor, so $T: V \rightarrow V$ induces a linear operator $\Lambda^n T: \Lambda^n V \rightarrow \Lambda^n V$ (explicitly, $(\Lambda^n T)(v_1 \wedge \dots \wedge v_n) = T(v_1) \wedge \dots \wedge T(v_n)$).
But $\dim(\Lambda^n V) = 1$, and any linear operator on a 1-dim. vector space is a scalar multiple of id. \Rightarrow define $\det(T) \in k$ such that $\Lambda^n T = \det(T) \text{id}$.

(This expresses the fact that T scales volume of parallelepipeds in V by a factor of $\det(T)$, without having to choose $\Lambda^n V \cong k$ to measure those volumes) ③

Using this definition of the determinant via $\Lambda^n T$, independence of choice of basis is manifest, and so is the fact that $\det(T_1 T_2) = \det(T_1) \det(T_2)$!

Linear algebra over rings: modules (Artin §14.1-14.2)

Let R be a commutative ring (with $1 \neq 0$) (ie. relax field axioms to not require multiplicative inverses). Plain examples $R = \mathbb{Z}, \mathbb{Z}/n, k[x], k[x_1, \dots, x_n]$.

Def: A module M over a ring R is a set with two operations:

- $+$: $M \times M \rightarrow M$ addition, st. $(M, +)$ is an abelian group.
- \times : $R \times M \rightarrow M$ scalar multiplication, st. $(ab)v = a(bv)$, $a(v+w) = av + aw$, $(a+b)v = av + bv$, $0v = 0$, $1v = v$.

Ex: • $R^n = \{(x_1, \dots, x_n) \mid x_i \in R\}$ with componentwise operations is the free module of rank n over R .

• any abelian group is a \mathbb{Z} -module ($n \cdot g = \overbrace{g + \dots + g}^{n \text{ times}}$) - check details (homework)

Def:

- $\Gamma \subset M$ spans M (or generating set) if every element of M is a (finite) linear combination $\sum a_i v_i$, $v_i \in \Gamma$, $a_i \in R$.
Equivalently: the map $\varphi: R^\Gamma \rightarrow M$, $(a_i) \mapsto \sum a_i v_i$ is surjective.
 M is finitely generated if it has a finite spanning set.
- the elements of $\Gamma \subset M$ are (linearly) independent if $\varphi: R^\Gamma \rightarrow M$ is injective, ie $\sum a_i v_i = 0$, $v_i \in \Gamma$, $a_i \in R \Rightarrow a_i = 0 \forall i$
- the elements of $\Gamma \subset M$ form a basis if $\varphi: R^\Gamma \rightarrow M$ is an isomorphism.
In this case, say M is a free module.

General fact about modules: nothing is true!

• A basis need not exist!

Ex: $M = \mathbb{Z}/n$ as \mathbb{Z} -module: $nx = 0 \forall x \in M$ so $\varphi: \mathbb{Z}^\Gamma \rightarrow M$ can't be injective!

• Even if M is free (admits a basis):

• a linearly independent set may not be a subset of a basis.

Ex: $M = \mathbb{Z}$ as \mathbb{Z} -module, \nexists basis $\ni 2$.

- a spanning set need not contain a subset which is a basis (4)
- Ex: $M = \mathbb{Z}$ as \mathbb{Z} -module, $\{4, 5\}$ span \mathbb{Z} (since $n = n \cdot 5 - n \cdot 4$)
but aren't independent ($5 \cdot 4 - 4 \cdot 5 = 0$), & neither subset $\{4\}$ or $\{5\}$ spans all of \mathbb{Z} .

- A submodule of a finitely generated module need not be finitely generated

Ex: $R = k[x_1, x_2, \dots]$ polynomials in ∞ many variables

$M = R$ as R -module is generated by the element 1.

$M' = \{ \text{polynomials whose constant term is zero} \} \subset M$ is a submodule, but not finitely gen^d (any finite subset only involves finitely many x_i 's, can't span the other x_k 's).

(by contrast, this holds for modules over Noetherian rings, including \mathbb{Z} , $k[x_1, \dots, x_n]$ and many others).

Def: \parallel M, N modules over R , a module homomorphism $\varphi \in \text{Hom}_R(M, N)$ is a map $\varphi: M \rightarrow N$ st. $\varphi(v+w) = \varphi(v) + \varphi(w)$ and $\varphi(av) = a\varphi(v)$.

Observe: $\text{Hom}_R(M, N)$ is itself an R -module: $(\varphi + \psi)(v) = \varphi(v) + \psi(v)$
 $(a\varphi)(v) = a\varphi(v)$.

For free modules, things work as expected: $\text{Hom}_R(R^m, R^n) \cong R^{m \times n}$

(φ is determined by images $\varphi(e_i) \in R^n$ of the basis vectors of R^m)

but we can have nonzero modules M, N st. $\text{Hom}_R(M, N) = 0!$

Ex: $R = k[x]$, $M = k$ with multiplication $(a_0 + a_1x + \dots) \cdot b = a_0b$.

then $\text{hom}_R(k, k[x]) = 0$ (because $1 \in k$ satisfies $x \cdot 1 = 0$

so must map to $\varphi(1) = p(x) \in k[x]$ st. $x p(x) = 0 \Rightarrow p = 0$.)

Remarks: • R is a module over itself (free module of rank 1)

A submodule of R is called an ideal: this is a subset $N \subset R$ st.

- N is an abelian subgroup of $(R, +)$

- $R \cdot N \subseteq N$: mult. by any element of R takes N to itself

Ex: Ideals in \mathbb{Z} are $n\mathbb{Z}$ } ie. generated by a single
 $k[x]$ are $p(x)k[x]$ } element. This is very special.

(\mathbb{Z} and $k[x]$ are "principal ideal domains". This has to do with Euclidean division algorithms: $\text{span}(p, q) = \text{span}(\text{gcd}(p, q))$.)

• The quotient of an R-module by a submodule is an R-module.

Ex: $\mathbb{Z}/n\mathbb{Z} = \mathbb{Z}/n$ as \mathbb{Z} -module

$k[x]/xk[x] = k$ as $k[x]$ -module (example above).

(The quotient of R itself by a submodule = ideal is, in fact, not just an R-module but also a ring in its own right).

The study of modules is a vast subject, which we won't study further, with one exception: we're returning to group theory, but we start with a short account of the classification of finitely generated abelian groups (= \mathbb{Z} -modules)

Theorem: || Any finitely generated abelian group is isom. to a product of cyclic groups
|| $G \cong (\mathbb{Z}/n_1 \times \dots \times \mathbb{Z}/n_k) \times \mathbb{Z}^l$

(+ using $\mathbb{Z}/mn \cong \mathbb{Z}/m \times \mathbb{Z}/n$ iff $\gcd(m,n) = 1$, can rearrange the finite factors eg. to arrange all $n_i =$ powers of primes).